Large-Scale Joint Rate and Power Allocation Algorithm Combined with Admission Control in Cognitive Radio Networks

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Abstract: In this paper, we investigate a dynamic spectrum sharing problem for the centralized uplink cognitive radio networks using orthogonal frequency division multiple access. We formulate a *large-scale* joint rate and power allocation as an optimization problem under quality of service constraint for secondary users and interference constraint for primary users. We also suggest admission control to find a feasible solution to the optimization problem. To implement the resource allocation on a large-scale, we introduce a notion of using the conservative factors α and β depending on the outage and violation probabilities. Since estimating instantaneous channel gains is costly and requires high complexity, the proposed algorithm pursues a practical and implementation-friendly resource allocation. Simulation results demonstrate that the *large-scale* joint rate and power allocation incurs a slight loss in system throughput over the instantaneous one, but it achieves lower complexity with less sensitivity to variations in shadowing statistics.

Index Terms: Cognitive radio (CR), geometric programming, large-scale fading, orthogonal frequency division multiple access (OFDMA), outage probability, resource allocation, small-scale fading, violation probability.

I. INTRODUCTION

Orthogonal frequency division multiple access (OFDMA) is a promising modulation and access scheme for the proposed future wireless network standard like 4G cellular networks. For the network based on OFDMA, due to the large capacity that can be provided by OFDMA, it could be possible that the system is under-utilized and more profits can be obtained by exploiting cognitive radio (CR). In CR, unlicensed secondary users (SUs) can access the spectrum resources leased to the licensed primary users (PUs) with spectrum overlay and spectrum underlay so that limited spectrum resource can efficiently be utilized [1]. In spectrum overlay, SUs are allowed to access spectrum resources only when PUs do not use this resource. In spectrum underlay, unlicensed SUs can share the spectrum resource with licensed PUs under an interference limit (or spectral mask) defined as a maximum allowed interference at primary receiving points.

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To successfully deploy spectrum underlay based cognitive radio networks (CRNs), two apparently conflicting constraints must be satisfied simultaneously:

- 1) The quality of service (QoS) constraint (in terms of minimum required signal-to-interference-plus-noise ratio (SINR)) for SUs at each subcarrier.
- 2) Interference constraint for PUs to be protected from any harmful interference caused by SUs, that results from sharing the common spectrum resource.

Therefore, to meet these two constraints simultaneously, joint rate and power allocation algorithm combined with admission control is a prerequisite for the CRNs.

In literature, given information on all channel gains is available, resource allocation algorithms under QoS and interference constraints in code division multiple access (CDMA) system were proposed in [2] and [3]. However, from the practical point of view, it is difficult for low-end SUs to fast and accurately track the instantaneous channel gains. Moreover, the resource allocation adaptive to fast variations in the channel gains will increase the complexity associated with frequent measurements and updates. Especially, a threshold called the “spectral mask” should be predetermined to protect PUs from any harmful interference caused by SUs in CRNs. Consequently, in order to determine the spectral mask, an exact channel gain information is necessary so that the efficiency of the spectrum usage could be degraded because of the overhead caused by frequent exchanges of channel gain information across CRNs. More flexible approach that exploits the averaged channel gain was proposed in [4], where the outage and violation probabilities against small-scale fading for secondary and primary user links were introduced in single-carrier wideband code division multiple access (WCDMA) multi-cell model.

In this paper, we propose a *large-scale* joint rate and power allocation algorithm combined with admission control for uplink OFDMA based CRNs. We are concerned with the variations in large-scale fading and introduce the concept of outage and violation events against small-scale fast fading. This idea is similar to that given in [4]. However, this paper considers multi-cell CRNs with multi-carrier channel assignment, and admission control is also incorporated into the resource allocation algorithm to obtain a feasible solution to the optimization problem. In the process of solving the optimization problem, if any subcarrier assigned to a SU cannot be supported in terms of QoS, admission control is initiated to assure the QoS constraint on each SU’s assigned subcarriers; otherwise we carry out the *large-scale* joint rate and power allocation without performing admission control. Our simulation results show that the

proposed *large-scale* resource allocation algorithm can considerably reduce the complexity with a slight loss in throughput, and the two conservative α and β factors have less sensitivity to variations in shadowing statistics which is desired for CR operation.

The rest of the paper is organized as follows. Section II describes the system model and defines mean channel gain. *Large-scale* constraints are first defined and then the corresponding resource allocation problem is formulated in Section III. Section IV presents the geometric programming and its transformation method. The proposed *large-scale* joint resource allocation algorithm is described in Section V. Section VI verifies the performance of the proposed algorithm by simulations. Finally, concluding remarks are stated in Section VII.

II. SYSTEM MODEL AND MEAN CHANNEL GAIN

In this section, we first describe the system model, and then define mean channel gain which is averaged over small-scale fading.

A. System Model

We consider M multi-cell OFDMA based CRNs where L SUs and one base station (BS) exist in each cell and the total number of OFDM subcarriers is K . In each cell, subcarriers are assigned to SUs exclusively so that there is no intra-cell interference, whereas subcarriers are shared among different cells and this will cause inter-cell interference. In this paper, we assume that all channel information, such as path loss, shadowing and geo-location of PUs and SUs, is *a priori* known to each BS. Based on this information, each BS allocates resources to the SUs in its own cell.

For the uplink OFDMA, the SINR of the i th SU in the m th cell at subcarrier k , $\mu_{i(m),k}$ can be expressed as:

$$\mu_{i(m),k} = \frac{g_{m,i(m),k}^{(s)} P_{i(m),k}}{\sum_{n=1, n \neq m}^M \sum_j g_{m,j(n),k}^{(s)} P_{j(n),k} + N_{i(m),k}} \quad (1)$$

where $i(m)$ represents the i th SU in the m th cell, $g_{m,i(m),k}^{(s)}$ is the channel gain from the i th SU to its corresponding BS in the m th cell at subcarrier k , $g_{m,j(n),k}^{(s)}$ is the channel gain from the j th SU in the n th cell to the BS in the m th cell, $P_{i(m),k}$ is the transmitted power of the i th SU in the m th cell at subcarrier k , and $N_{i(m),k}$ is the i th SU's noise power at subcarrier k . We assume that $N_{i(m),k} = N_o B_k$ for all SUs, where N_o is one-sided noise power spectral density and B_k is the k th subcarrier bandwidth.

B. Mean Channel Gain

In general, it is difficult to estimate the instantaneous channel gains, and adjusting the power and rate allocation to the changes in small-scale fading could increase the system complexity and cost. For this reason, we assume that the mean channel gains (path loss and shadowing) averaged over small-scale fading (Rayleigh fading) are available for the resource allocation on a large-scale. The channel gain from the i th SU to the

corresponding m th receiving point at subcarrier k , $g_{m,i(m),k}^{(s)}$ can be decomposed into

$$g_{m,i(m),k}^{(s)} = \sigma_{m,i(m),k}^{(s)} \bar{g}_{m,i(m),k}^{(s)} \quad (2)$$

where $\sigma_{m,i(m),k}^{(s)}$ is the small-scale fading with mean value normalized to one at subcarrier k , and $\bar{g}_{m,i(m),k}^{(s)}$ represents the mean channel gain, i.e., *local average* (with respect to small-scale fading) of $g_{m,i(m),k}^{(s)}$.

III. LARGE-SCALE CONSTRAINT AND PROBLEM FORMULATION

In this section, we define *large-scale* QoS and interference constraints, respectively. With defined *large-scale* constraints, we introduce the outage and violation probability constraints, respectively, and then formulate the *large-scale* optimization problem.

A. Large-Scale QoS Constraint

We can express an instantaneous QoS constraint for the i th SU in the m th cell at subcarrier k as follows:

$$\mu_{i(m),k} \geq \gamma_{i(m),k} \quad (3)$$

where $\mu_{i(m),k}$ is an instantaneous SINR of the i th SU in the m th cell at subcarrier k , as given in (1) and $\gamma_{i(m),k}$ is the minimum required SINR for the i th SU in the m th cell at subcarrier k . By replacing the instantaneous channel gain in (1) with the mean channel gain defined in (2), we can express an averaged SINR of the i th SU at subcarrier k , $\bar{\mu}_{i(m),k}$ as:

$$\bar{\mu}_{i(m),k} = \frac{\bar{g}_{m,i(m),k}^{(s)} P_{i(m),k}}{\sum_{n=1, n \neq m}^M \sum_j \bar{g}_{m,j(n),k}^{(s)} P_{j(n),k} + N_o B_k} \quad (4)$$

With the averaged SINR, the *large-scale* QoS constraint can be formulated as

$$\bar{\mu}_{i(m),k} \geq \alpha \gamma_{i(m),k} \quad (5)$$

where α acts as a conservative factor that implies a kind of margin for the QoS constraint.

Then, we can define the outage event as that occurs when the instantaneous QoS constraint in (3) is not satisfied, given the *large-scale* QoS constraint in (5) is satisfied. Therefore, the outage probability constraint for *large-scale* QoS requirements on the secondary links is defined as:

$$\Pr[\mu_{i(m),k} < \gamma_{i(m),k} \mid \bar{\mu}_{i(m),k} \geq \alpha \gamma_{i(m),k}] \leq \delta^{(s)} \quad (6)$$

where some $\alpha > 1$ and $\delta^{(s)}$ denotes the predetermined maximum outage probability allowed for SUs at each subcarrier.

B. Large-Scale Interference Constraint

Although the primary and secondary systems exploit different channel access schemes, since they share the common channel, total interference induced by SUs to primary receiving point q

can be obtained by a linear sum of all interferences at each sub-carrier. The instantaneous sum interference induced by SUs to the primary receiving point q , η_q and the instantaneous interference constraint can be expressed as follows:

$$\eta_q = \sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} g_{q,i(m),k}^{(p)} P_{i(m),k} \quad (7)$$

$$\eta_q \leq T_q \quad (8)$$

where $g_{q,i(m),k}^{(p)}$ is the channel gain from the i th SU in the m th cell to the primary receiving point q at subcarrier k , $\mathbf{S}_{i(m)}$ is the set of subcarriers assigned to the i th SU and T_q denotes the tolerable interference limit at primary receiving point q , $q = 1, 2, \dots, Q$.

Similar to the above *large-scale* QoS constraint case, if we replace the instantaneous channel gain in (7) by the mean channel gain, an averaged sum interference, $\bar{\eta}_q$ and the *large-scale* interference constraint can be formulated as:

$$\bar{\eta}_q = \sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} \bar{g}_{q,i(m),k}^{(p)} P_{i(m),k} \quad (9)$$

$$\bar{\eta}_q \leq \beta T_q \quad (10)$$

where β acts as a conservative factor that implies a kind of margin for the interference constraint.

The violation probability constraint for *large-scale* interference limits on the primary receiving points can be defined as:

$$\Pr[\eta_q > T_q \mid \bar{\eta}_q \leq \beta T_q] \leq \delta^{(p)} \quad (11)$$

where some $\beta < 1$ and $\delta^{(p)}$ denotes the predetermined maximum interference violation probability allowed for primary receiving points.

To ensure that the *large-scale* QoS and interference constraints defined in (5) and (10), respectively, are effective, the two conservative factors $\alpha > 1$ and $\beta < 1$ should be estimated to meet the constraints on outage and violation probabilities defined (6) and (11), respectively.

C. Problem Formulation

Our goal is to find an optimal resource allocation solution which maximizes the total sum rate of the system under the constraints (5), (6), (10), and (11). However, only after we obtain the solution satisfying the *large-scale* QoS and interference constraints, we can see whether the constraints on outage and violation probabilities are satisfied. For this reason, we divide a total resource allocation problem into two sub-problems such as *large-scale* optimization problem and outage and violation events check problem.

We first formulate the *large-scale* optimization problem under the maximum power constraint and *large-scale* constraints (i.e., QoS and interference constraints, (5) and (10), respectively). This *large-scale* optimization problem can be expressed as:

$$\text{maximize } \sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} R_{i(m),k} \quad (12)$$

subject to

$$\bar{\mu}_{i(m),k} \geq \alpha \gamma_{i(m),k}$$

$$\bar{\eta}_q \leq \beta T_q$$

$$\sum_{k \in \mathbf{S}_{i(m)}} P_{i(m),k} \leq P_{i(m)}^{max}$$

where $R_{i(m),k}$ represents the i th SU's data rate at subcarrier k , given by $R_{i(m),k} = B_k \log_2(1 + \tau_{i(m)} \bar{\mu}_{i(m),k})$, $\tau_{i(m)}$ is an SNR gap of the i th SU according to the modulation format and bit error rate (BER) requirement, $P_{i(m)}^{max}$ is the maximum transmit power allowed to the i th SU. In this paper, we assume that B_k is the same for all subcarriers, i.e., $B_k = B$ and $\tau_{i(m)}$ is equal to 1.

The above *large-scale* optimization problem is an intractable nonlinear optimization problem that may appear to be NP-hard problems [5], [6]. However, we will suggest the method to transform the proposed optimization problem into geometric programming (GP) which can be transformed into the convex optimization problem [5], [6]. In the next section, we discuss about the GP and then transform the optimization problem in (12) into GP.

IV. TRANSFORMATION OF THE OPTIMIZATION PROBLEM

In this section, we first introduce the GP and then transform the proposed optimization problem into GP in standard form.

A. Geometric Programming

GP is a type of mathematical optimization problem which is nonlinear, non-convex. However, because an optimization problem formulated in GP format can be converted into a convex optimization problem, a local optimum could also be a global optimum and a global optimum can always be computed very efficiently [5], [6].

Let $\vec{x} = (x_1, x_2, \dots, x_n)$ denote a vector with component x_i . A real valued function f of $\vec{x}$ is defined as

$$f(\vec{x}) = c x_1^{d_1} x_2^{d_2} \dots x_n^{d_n} \quad (13)$$

where the multiplicative constant $c > 0$ and the exponential components $d_i \in \mathbf{R}$, $i = 1, 2, \dots, n$, is called a monomial function or monomial.

A function which is a sum of one or more monomials is called a posynomial function or posynomial and it can be expressed as

$$f(\vec{x}) = \sum_k^K c_k x_1^{d_{1(k)}} x_2^{d_{2(k)}} \dots x_n^{d_{n(k)}} \quad (14)$$

where $c_k > 0$ and $d_{i(k)} \in \mathbf{R}$ for $i = 1, 2, \dots, n$ and $k = 1, 2, \dots, K$.

GP in standard form is an optimization problem of the form which minimizes a posynomial objective function subject to posynomial upper bound inequality constraints (i.e., less than equal to one) and monomial equality constraints (i.e., equal to one):

$$\text{minimize } f_0(\vec{x}) \quad (15)$$

subject to

$$f_i(\vec{x}) \leq 1, i = 1, 2, \dots, m,$$

$$g_j(\vec{x}) = 1, j = 1, 2, \dots, p$$

where $f_i, i = 0, 1, \dots, m$ are posynomial functions, $g_j, j = 1, 2, \dots, p$ are monomial functions, and $\vec{x}$ is the optimization variable.

While GP in standard form is not a convex optimization problem, GP can be converted into the convex optimization problem with a logarithm change of the variables and multiplicative constants, and a logarithm transformation of the objective and constraint functions [6].

B. Transformation Into Geometric Programming

We need to transform the proposed optimization problem into GP in standard form to obtain a solution to the proposed optimization problem (12). To satisfy the condition on the GP in standard form, we make some manipulation of the objective function in (12). Maximizing the objective function expressed as the sum of $\log_2(1 + \text{SINR})$ in (12) is equivalent to minimizing the product of $1/(1 + \text{SINR})$. Thus, we can convert the problem that maximizes the objective function into the equivalent one which minimizes the product of $1/(1 + \text{SINR})$. However, the form of $1/(1 + \text{SINR})$ is a ratio of two posynomials and minimizing a ratio of two posynomials is one of the truly non-convex class of problems [7]. To solve this problem, two successive approximation methods, i.e., a logarithmic approximation method and a single condensation method, were introduced in [8], and hence we use these two successive approximation methods along with high SINR approximation as follows:

1) High SINR approximation for GP

If SINR is much greater than one, $\log_2(1 + \text{SINR})$ can be approximated to $\log_2(\text{SINR})$. Therefore, $1/(1 + \text{SINR})$ can approximately be converted into $1/\text{SINR}$ and the objective function is no longer a ratio of two posynomials. However, this approximation is reasonable only when the signal level is much higher than the interference level.

2) Single condensation approximation method for GP [7]

To solve the problem that the objective function is a ratio of two posynomials, we can employ the arithmetic-geometric mean inequality method which can transform the posynomial into the product of monomials. The arithmetic-geometric mean inequality indicates that $\sum_i a_i b_i \geq \prod_i b_i^{a_i}$, where $\vec{a} \succeq 0, \vec{b} \succ 0, \vec{1}^T \vec{a} = 1$. Let $g_i = a_i b_i$ and then we can express this inequality as $\sum_i g_i \geq \prod_i (g_i/a_i)^{a_i}$. This inequality becomes tight with equality, if $a_i = g_i / \sum_i g_i$ for all i , which meet the condition that $\vec{a} \succeq 0$ and $\vec{1}^T \vec{a} = 1$.

3) Logarithmic approximation method for GP [9]

A non-convex problem involving $\log_2(1 + \text{SINR})$ can be approximated to $x \log_2(\text{SINR}) + y$ for some constants x and y satisfying the following conditions:

$$x \log_2(z) + y \leq \log_2(1 + z) \quad (16)$$

$$x = \frac{z_0}{1 + z_0}$$

$$y = \log_2(1 + z_0) - \frac{z_0}{1 + z_0} \log_2(z_0)$$

where the inequality becomes tight with equality at a chosen value z_0 , when the constants x and y are determined as specified above.

In the next subsection, we are going to select the most appropriate approximation method for our proposed optimization problem by comparing the results obtained from these three approximation methods.

C. Two-User Two-Subcarrier Example

Since the analytic comparison of the performance among these approximation methods seems to be intractable, in this paper we carry out a computer simulation under the same environment. The goal of the proposed optimization problem is to maximize the total sum rate of the system. Therefore, from the optimal point of view, it can be said that the method which yields the largest sum rate under the same *large-scale* QoS and interference constraints is the most suitable method for the proposed optimization problem. We compare the sum rates obtained from three different approximation methods:

- 1) High SINR approximation
- 2) single condensation approximation
- 3) logarithmic approximation

for the simple two-user two-subcarrier example.

In this example, we assume that each SU has the maximum transmit power 4W and the same minimum required SINR, 3 dB at each subcarrier. The propagation model assumes the operation in a suburban environment and considers long-term fading (path loss and shadowing). Path loss exponent is set to 3.5 and shadowing for each SU is modeled as an independent log-normal random variable with standard deviation 6 dB. The tolerable interference limit at the primary receiver is determined to yield the desired SINR of 23 dB. To compare the sum rate achieved from each approximation method, we generate 100 different shadowing realizations under the same *large-scale* QoS and interference constraints with the fixed channel allocation and positions of two users.

From Fig. 1, we can see that logarithmic and single condensation approximation methods always perform better than high SINR approximation method in terms of the achieved sum rate. However, since the two logarithmic and single condensation methods result in almost similar outcome with a slight difference, the performance of these two approximation methods needs to be compared in detail, and we define a variable θ as

$$\theta = S_{\log} - S_{s.c} \quad (17)$$

where $S_{\log}$ indicates the total sum rate obtained from the logarithmic approximation method and $S_{s.c}$ represents the total sum rate achieved from the single condensation method.

In Fig. 2, we plot the instantaneous value of θ obtained from every trial as well as the average of θ over all trials. We can observe that not only the average of θ is greater than zero but

Fig. 1. Sum rates obtained from three different approximation methods.

also each value of θ is greater than zero in most simulation trials. Therefore, we could consider the logarithmic approximation method to be the most suitable for our proposed optimization problem based on the simulation results obtained from this two-user two-subcarrier example.

D. Transformation with Logarithmic Approximation

From the previous subsection, we verified that a logarithmic approximation method is the most suitable for our proposed optimization problem. Therefore, we employ the logarithmic approximation method to transform the objective function in our proposed optimization problem (12) into GP in standard form. From the transformation process, an optimal solution can be obtained by solving the following equivalent optimization problem which is GP in standard form:

$$\text{minimize } \prod_{m=1}^M \prod_{i=1}^L \prod_{k \in \mathbf{S}_{i(m)}} \frac{1}{\frac{x_{i(m),k}}{\bar{\mu}_{i(m),k}} 2^{y_{i(m),k}}} \quad (18)$$

subject to

$$\begin{aligned} & \frac{\alpha \gamma_{i(m),k}}{\bar{g}_{m,i(m),k}^{(s)}} P_{i(m),k}^{-1} \sum_{n=1, n \neq m}^M \sum_j \bar{g}_{m,j(n),k}^{(s)} P_{j(n),k} \\ & + \frac{\alpha \gamma_{i(m),k}}{\bar{g}_{m,i(m),k}^{(s)}} P_{i(m),k}^{-1} N_o B \leq 1, \\ & \frac{\sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} \bar{g}_{q,i(m),k}^{(p)} P_{i(m),k}}{\beta T_q} \leq 1, \\ & (P_{i(m)}^{max})^{-1} \sum_{k \in \mathbf{S}_{i(m)}} P_{i(m),k} \leq 1 \end{aligned}$$

where $x_{i(m),k} = \bar{\mu}_{i(m),k} / (1 + \bar{\mu}_{i(m),k})$ and $y_{i(m),k} = \log_2(1 + \bar{\mu}_{i(m),k}) - (\bar{\mu}_{i(m),k} / (1 + \bar{\mu}_{i(m),k})) \log_2(\bar{\mu}_{i(m),k})$. Values of $x_{i(m),k}$ and $y_{i(m),k}$ are determined by the iterative method as stated in [9].

A detailed procedure for transforming the optimization problem (12) into the equivalent one (18) can be found in the appendix.

Fig. 2. Sum rate difference between logarithmic approximation and single condensation approximation methods.

Once the optimal solution is obtained from the optimization problem (18), we proceed to the second sub-problem, outage and violation events check problem. With the solution achieved from the optimization problem, we can evaluate the outage and violation probabilities to see if the obtained solution satisfies both outage and violation probability constraints, (6) and (11), respectively. If the obtained solution satisfies both outage and violation constraints, it is determined as a final optimal solution; otherwise we need to solve the optimization problem (18) again with newly updated α and β . The overall procedure will be described in the next section.

V. LARGE-SCALE JOINT POWER AND RATE ALLOCATION WITH ADMISSION CONTROL

In this section, we present the procedure of the proposed algorithm to find a solution to the optimization problem (18) under outage and violation probability constraints. Since the outage and violation probabilities depend on the solutions of the optimization problem, we propose the iterative algorithm to find out appropriate α and β factors and the corresponding optimal solutions. The objective here is to maximize the total throughput while satisfying users' QoS requirements at each subcarrier. However, since higher transmit power of one user increases interference levels to other users, there may not be a feasible solution to meet QoS requirements for all users under the interference constraints. For this reason, we incorporate admission control into resource allocation algorithm such that QoS and interference constraints can be satisfied simultaneously.

The proposed *large-scale* resource allocation algorithm combined with admission control is designed as follows:

- step 1: Initialize $\alpha = 1$ and $\beta = 1$.
- step 2: Solve the *large-scale* optimization problem in (18) with the current α and β .
- step 3: If a feasible solution satisfying both *large-scale* QoS and interference constraints is obtained, compute and store each user's SINR based on the solution obtained by current α and β , and then go to step 4; otherwise go to step 6.

step 4: Compute the outage and violation probabilities and check whether they satisfy both outage and violation probabilities constraints in (6) and (11), respectively. If the feasible solution obtained from step 3 satisfies both outage and violation constraints, finish and allocate obtained resources to the users; otherwise go to step 5.

step 5: Update the conservative factors, α and β as follows:

if outage constraint in (6) is violated, $\alpha = \alpha + \Delta\alpha$

if violation constraint in (11) is violated, $\beta = \beta - \Delta\beta$

where $\Delta\alpha$ and $\Delta\beta$ are predetermined small adjustment values.

After updating α and β , go back to step 2 with the updated α and β .

step 6: (*Admission control*) If a currently used α is 1, solve the optimization problem in step 2 again without QoS constraint (i.e. setting α to be zero) and calculate SINR to set a criterion for the admission control; otherwise use the SINR measured in step 3 as a criterion for the admission control.

step 7 : (*Admission control*) Perform the admission control to prevent the worst user producing the lowest SINR of all users and all subcarriers from using the corresponding subcarrier. After step 7, return to step 2.

The process of estimating appropriate α and β satisfying outage and violation probability constraints (i.e., step 4 and 5) does not need to be done again as long as the given network condition and channel allocation do not change. Therefore, the proposed algorithm can be implemented in two modes such as *tuning* mode and *blind* mode. In a given network and channel allocation, the proposed algorithm will do all steps (i.e., from step 1 to 7) during the *tuning* mode. Through *tuning* mode, we can estimate the proper α and β and the corresponding solutions to the optimization problem. For the *blind* mode, since the α and β obtained from *tuning* mode can continuously be used (while the given network condition and channel allocation do not change), we are required to implement only several steps (i.e., step 2, 3, 6, and 7). Note that if outage and/or violation occur during the *blind* mode, adaptive modulation and coding (AMC) may be implemented to adjust the data rate for a given QoS at each subcarrier.

VI. SIMULATION RESULTS

We evaluate the performance of the proposed algorithm in IEEE 802.22 Wireless Regional Area Network (WRAN) which is the first cognitive radios based wireless standard [10], [11]. We consider the co-existence scenario where one primary network and two secondary network coexist. To obtain a protect contour and keep-out region defined in [11], we assume that the distance from a primary receiver to the BS in each secondary network is 26 km and two cells are apart from each other with the distance of 4 km. In each cell, one BS is located at the center of the cell and three SUs are randomly generated at the edge of the cell to make the sum interference to primary receiver severe. The propagation model assumes the operation in a suburban environment and takes into consideration path loss and shadowing. Path loss exponent is set to be 3.5 and shadowing for each SU is modeled as an independent log-normal random variable with standard deviation 6 dB and 8 dB. The ten-path Rayleigh fading

Fig. 3. Sum rate comparison of the proposed algorithm and instantaneous resource allocation method.

model is considered to simulate the frequency selective fading channel. We consider OFDMA system with 12 subcarriers in total and 4 subcarriers are randomly allocated to each SU in each cell. In each cell, subcarriers are assigned to SUs exclusively so that there is no intra-cell interference. However, subcarriers are shared among different cells and this will cause inter-cell interference. The overall bandwidth is 0.36MHz (i.e., 3KHz per sub-channel). We assume that all SUs have the same total transmit power, 4W and the same minimum required SINR, 3 dB at every subcarrier. Maximum outage and interference violation probability is set to be 5% and 0.5%, respectively. The adjustment values for conservative factors are empirically chosen to be $\Delta\alpha = 1$ and $\Delta\beta = 0.05$. The tolerable interference limit at the primary receiver is determined to yield the desired SINR of 23 dB. To check whether the solutions obtained from the optimization problem in (18) satisfy outage and violation probabilities, we generate 10,000 different small-scale fading events.

A. Throughput Performance

To investigate the throughput performance of the proposed algorithm, we compare the sum rate obtained from the proposed algorithm to the one obtained from allocating resources according to the instantaneous channel gains. We assume that the frame length is on the order of 10 to 20 msec while the channel coherence time is typically on the order of 2.5 msec [12], in which case small-scale fading changes 4 to 8 times every frame transmission. Typically, large-scale fading changes once every tens of frames, depending on the propagation environments, and hence we assume that small-scale fading approximately changes 100 times per large-scale fading. The sum rate of the instantaneous resource allocation is obtained by taking the average of data rates achieved from each trial.

In Fig. 3, we can see that the sum rate of the proposed algorithm incurs about 2.64% of loss when it compares to the sum rate of the instantaneous resource allocation. Since 5% outage probability is assumed in the proposed algorithm, it will incur additional loss in the outage compared to the instantaneous resource allocation. However, the proposed algorithm

Fig. 4. Outage probability for shadowing with standard deviation 6 dB.

Fig. 6. Violation probability for shadowing with standard deviation 6 dB.

Fig. 5. Outage probability for shadowing with standard deviation 8 dB.

Fig. 7. Violation probability for shadowing with standard deviation 8 dB.

still achieves 1/100 times less frequent power adaptation with a slight loss in sum rate. Also, the simulation results show that the proposed algorithm is not sensitive to the ratio factor between large-scale and small-scale fading as long as it ranges from 10 to 1000.

B. Sensitivity of α and β to the Variations in Shadowing

To investigate whether the achieved α and β are sensitive to variations in shadowing, we simulate the outage and violation probabilities with the different shadowing whose standard deviation is 6 dB and 8 dB, respectively. In Figs. 4–7, we present the computed outage probability and violation probability with standard deviation 6 dB and 8 dB, respectively. From the simulation results, when estimated $\alpha = 4$ and $\beta = 0.6$, we can observe that every outcome of all trials satisfies both maximum outage and violation probabilities in both cases where the standard deviation of shadowing is 6 dB and 8 dB, respectively. Therefore, by estimating proper α and β during the *training* mode, the estimated α and β can reliably be used during the *blind* mode even with slight variations in shadowing, so that we do not need to

estimate α and β frequently, resulting in reduced overhead.

VII. CONCLUSION

We have proposed a framework for dynamic spectrum sharing between primary and secondary networks. To overcome the complexity problem caused by tracking the channel gains instantaneously, the proposed algorithm allocates resources to users on a large-scale while satisfying both *large-scale* QoS and interference constraints under the constraints on the outage and violation probabilities. Introducing two conservative factors α and β makes it possible for the system to implement more flexible power allocation over conventional one, leading to a practical and implementation-friendly resource allocation for CRNs. As the large-scale fading changes less, the effectiveness of the proposed algorithm becomes better. Therefore, the proposed algorithm could be suitable for the IEEE 802.22 WRAN where customer premises equipments (which referred to as users in this paper) are considered to be fixed terminals. Further extension of the proposed algorithm to ad-hoc based CRNs and considering

user-based fairness in the optimization problem are worth pursuing.

APPENDIX

By logarithmic approximation (16), the objective function in (12) can be expressed as:

$$\begin{aligned}
 \sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} R_{i(m),k} &= \sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} B_k \log_2(1 + \bar{\mu}_{i(m),k}) \\
 &= \sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} B_k (x_{i(m),k} \log_2(\bar{\mu}_{i(m),k}) + y_{i(m),k}) \\
 &= \sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} B_k (\log_2(\bar{\mu}_{i(m),k})^{x_{i(m),k}} + \log_2(2^{y_{i(m),k}})) \\
 &= \sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} B_k \log_2((\bar{\mu}_{i(m),k})^{x_{i(m),k}} 2^{y_{i(m),k}}) \quad (19)
 \end{aligned}$$

where $x_{i(m),k} = \bar{\mu}_{i(m),k} / (1 + \bar{\mu}_{i(m),k})$ and $y_{i(m),k} = \log_2(1 + \bar{\mu}_{i(m),k}) - (\bar{\mu}_{i(m),k} / (1 + \bar{\mu}_{i(m),k})) \log_2(\bar{\mu}_{i(m),k})$.

We assume that the bandwidth of all subcarriers is the same, i.e., a constant value $B_k = B$, and $\log_2(x)$ is an increasing function with value of $x > 1$. Therefore, with the approximated objective function in (19), the optimization problem (12) can be formulated as:

$$\text{maximize } \prod_{m=1}^M \prod_{i=1}^L \prod_{k \in \mathbf{S}_{i(m)}} \left((\bar{\mu}_{i(m),k})^{x_{i(m),k}} 2^{y_{i(m),k}} \right) \quad (20)$$

subject to

$$\begin{aligned}
 \frac{\bar{g}_{m,i(m),k}^{(s)} P_{i(m),k}}{\sum_{n=1, n \neq m}^M \sum_j \bar{g}_{m,j(n),k}^{(s)} P_{j(n),k} + N_o B} &\geq \alpha \gamma_{i(m),k}, \\
 \sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} \bar{g}_{q,i(m),k}^{(p)} P_{i(m),k} &\leq \beta T_q, \\
 \sum_{k \in \mathbf{S}_{i(m)}} P_{i(m),k} &\leq P_{i(m)}^{max}.
 \end{aligned}$$

To satisfy the condition on the objective function of GP in standard form, the optimization problem stated (20) can be transformed into the equivalent problem which is GP in standard form:

$$\text{minimize } \prod_{m=1}^M \prod_{i=1}^L \prod_{k \in \mathbf{S}_{i(m)}} \frac{1}{(\bar{\mu}_{i(m),k})^{x_{i(m),k}} 2^{y_{i(m),k}}} \quad (21)$$

subject to

$$\begin{aligned}
 \frac{\alpha \gamma_{i(m),k}}{\bar{g}_{m,i(m),k}^{(s)}} P_{i(m),k}^{-1} \sum_{n=1, n \neq m}^M \sum_j \bar{g}_{m,j(n),k}^{(s)} P_{j(n),k} \\
 + \frac{\alpha \gamma_{i(m),k}}{\bar{g}_{m,i(m),k}^{(s)}} P_{i(m),k}^{-1} N_o B \leq 1,
 \end{aligned}$$

$$\begin{aligned}
 \frac{\sum_{m=1}^M \sum_{i=1}^L \sum_{k \in \mathbf{S}_{i(m)}} \bar{g}_{q,i(m),k}^{(p)} P_{i(m),k}}{\beta T_q} &\leq 1, \\
 (P_{i(m)}^{max})^{-1} \sum_{k \in \mathbf{S}_{i(m)}} P_{i(m),k} &\leq 1.
 \end{aligned}$$

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